



*Inria*

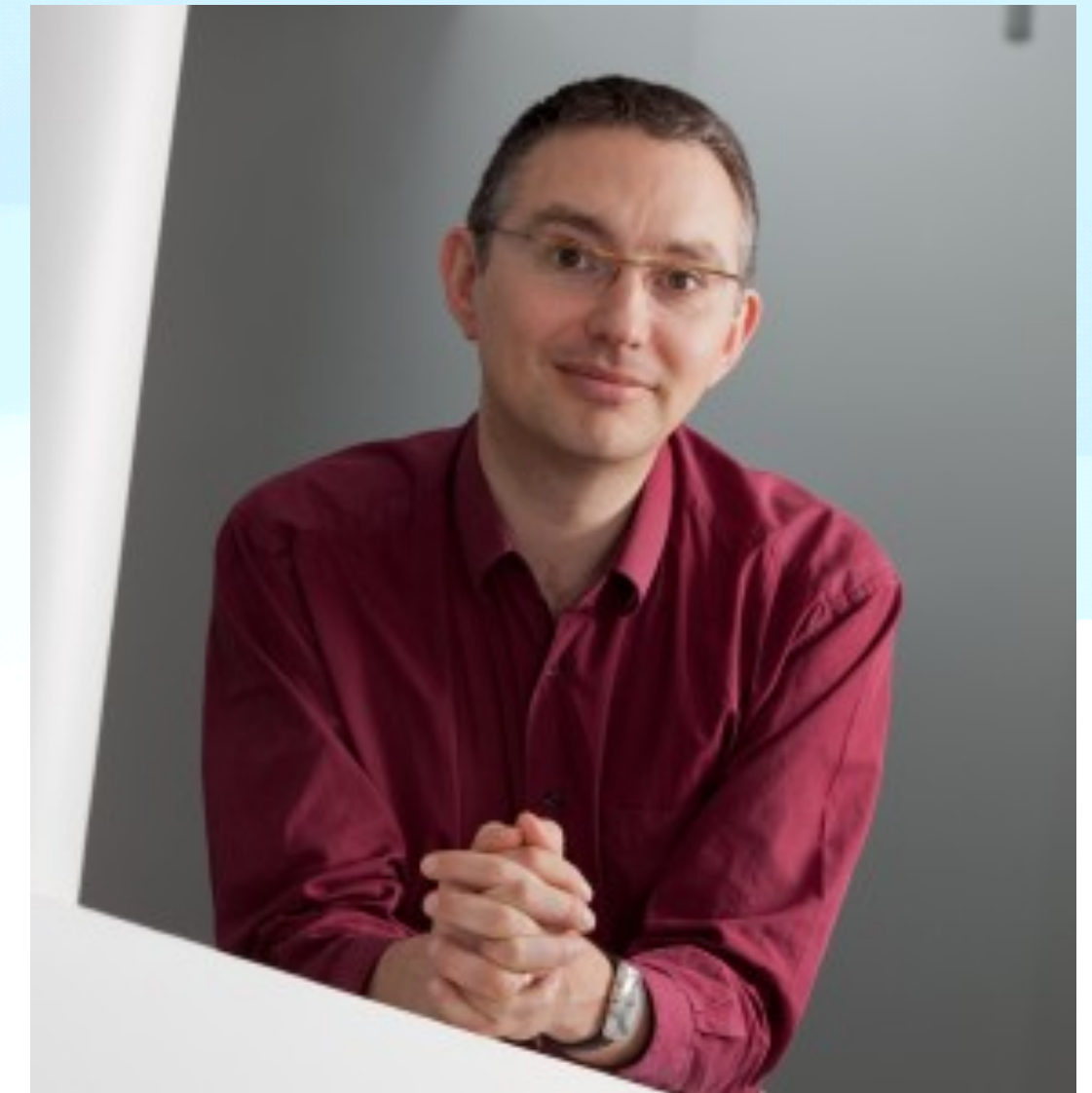
# Existence of optima in sparse matrix factorization and sparse ReLU networks training



**Léon Zheng**



**Elisa Riccietti**



**Rémi Gribonval**

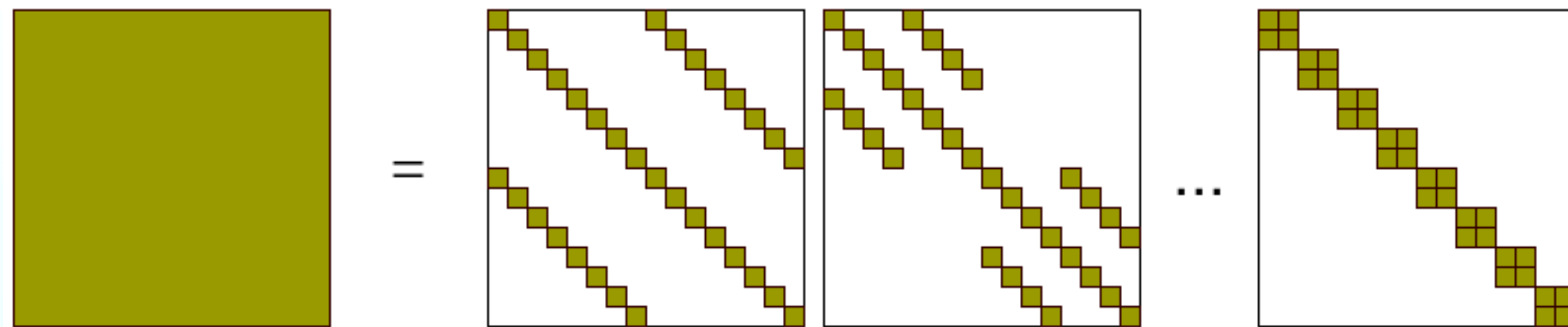
# Sparse matrix factorization

**OBJECTIVES:** Given  $A$ , find some *sparse* matrices  $X_\ell, \ell = 1, \dots, L$ , such that:

$$A \approx X_1 \dots X_L$$

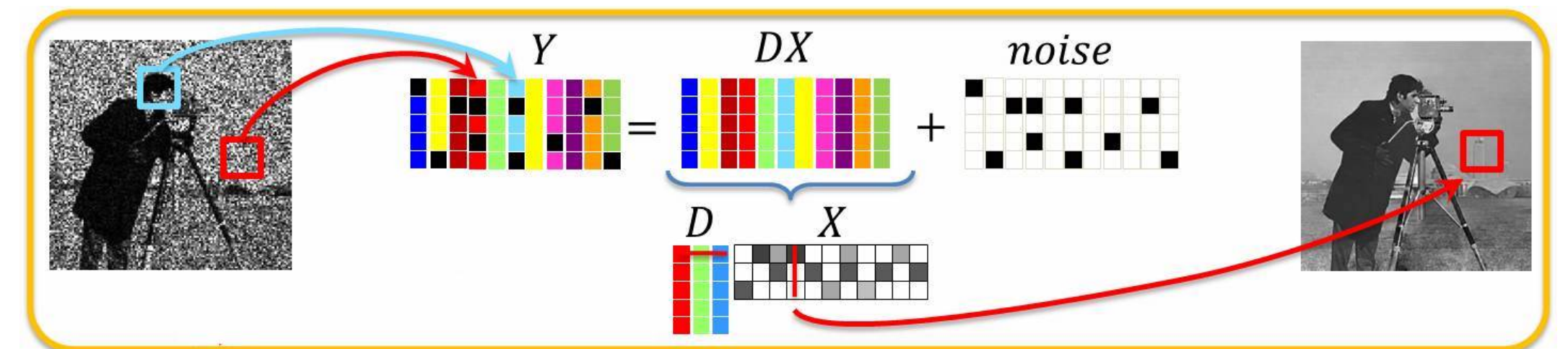
**APPLICATIONS:** Accelerating matrix-vector multiplication, data analysis, etc.

$$Ax \approx X_1(X_2 \dots (X_L x)), \forall x$$



*Fast Fourier Transformation*

$$Y = DX, \quad X \text{ sparse}$$



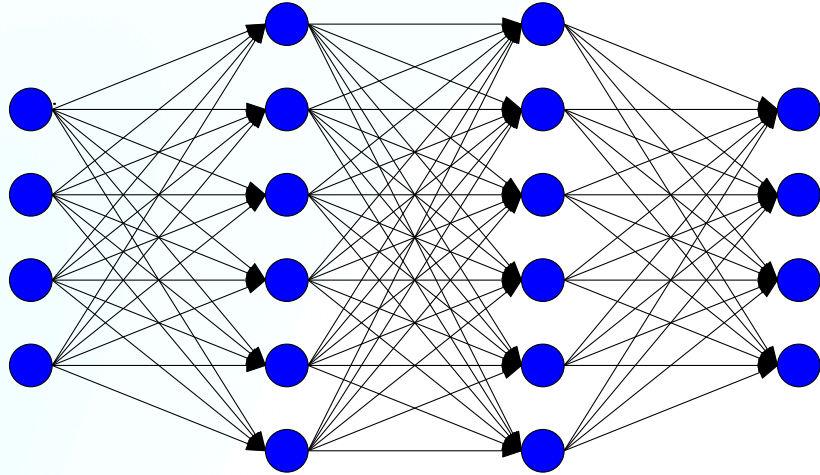
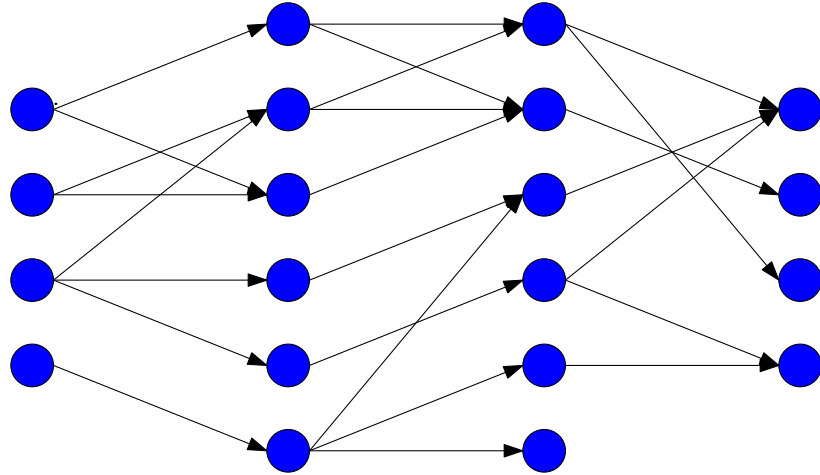
*Dictionary learning*

# ReLU neural networks and sparse ReLU neural networks

**DEFINITIONS:** Given *weight matrices*  $W^{(\ell)}$  and *bias vectors*  $b^{(\ell)}$ ,  $\ell = 1, \dots, L$

$$x \mapsto W^{(L)} \sigma(\dots \sigma(W^{(1)}x + b^{(1)}) + \dots) + b^{(L)}$$

$\sigma : \mathbb{R} \mapsto \mathbb{R} : \sigma(x) = \max(0, x)$  is the ReLU activation function

Conventional Deep Neural Networks	Sparse Deep Neural Networks
	
<b>The weight matrices are dense</b>	<b>The weight matrices are sparse</b>

# Sparse matrix factorization formulation

## OPTIMIZATION FORMULATIONS:

Given  $A$  and  $\mathcal{E}_j$  some sets of *sparse* matrices, solve:

$$\min_{S^{(1)}, \dots, S^{(L)}} \|A - \prod_{j=1}^L S^{(j)}\|_F^2 \text{ subject to: } S^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$

Choice of sparse matrices set  $\mathcal{E}_j$

- $k$ -sparse per row,
- $k$ -sparse per column
- $k$ -sparse in total

**COMPLEXITY:** Problem is **NP-hard** in general (Malik, IPL 2017), (S.Foucart, H. Rauhut, ANNA 2013)

# Sparse ReLU neural networks (NNs) training

## OPTIMIZATION FORMULATIONS:

Given data set  $\mathcal{D} := (X, Y)$  and  $\mathcal{E}_j$  some sets of *sparse* matrices, solve:

$$\min_{W^{(j)}, b^{(j)}} \|Y - W^{(L)} \sigma(\dots \sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

$$\text{subject to: } W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$

Practical choice of sparse matrices set  $\mathcal{E}_j$ :  $k$ -sparse in total

(J. Frankle, M. Carbin, ICLR 2019), (S. Han, H. Mao, W-J. Dally, ICLR 2016)

**COMPLEXITY:** Not known yet.

Expected to be difficult since training classical ReLU NNs is **NP-hard**.

(R. Livni, S. Shalev-Shwartz, O. Shamir, NeuRIPS 2014), (D. Boob, S-S. Dey, G. Lan, Discrete Optimization 2022)

→ How to deal with these problems?

# Banded to sparse matrix factorization

SPECIAL CASE OF SPARSE MATRIX FACTORISATION

SPARSE MATRIX  
FACTORISATION

$$\min_{S^{(1)}, \dots, S^{(L)}} \|A - \prod_{j=1}^L S^{(j)}\|_F^2 \text{ subject to: } S^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$



FIXED SUPPORT  
MATRIX  
FACTORISATION




- $L = 2$
- $(\mathcal{E}_1, \mathcal{E}_2)$ : set of matrices whose **support** are included in  $I$  and  $J$


$$\min_{X, Y} \|A - XY^T\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$

# Fixed support matrix factorization (FSMF)

$$\min_{X,Y} \|A - XY^T\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$

$$A \approx \begin{matrix} & \mathbf{X} & & \\ & \begin{matrix} ? & ? & 0 & ? \\ 0 & ? & ? & 0 \\ ? & 0 & ? & 0 \\ 0 & ? & 0 & ? \end{matrix} & \times & \begin{matrix} \mathbf{Y}^T \\ \begin{matrix} 0 & ? & 0 & ? & 0 \\ ? & ? & 0 & 0 & ? \\ ? & 0 & ? & ? & 0 \\ ? & 0 & ? & 0 & ? \end{matrix} \end{matrix}$$

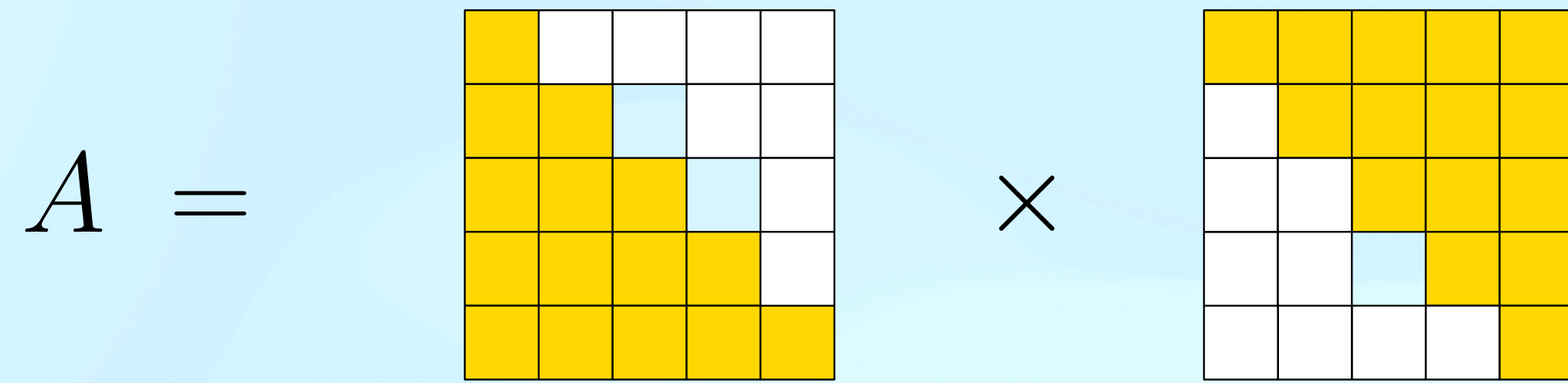
 inside support

 outside support

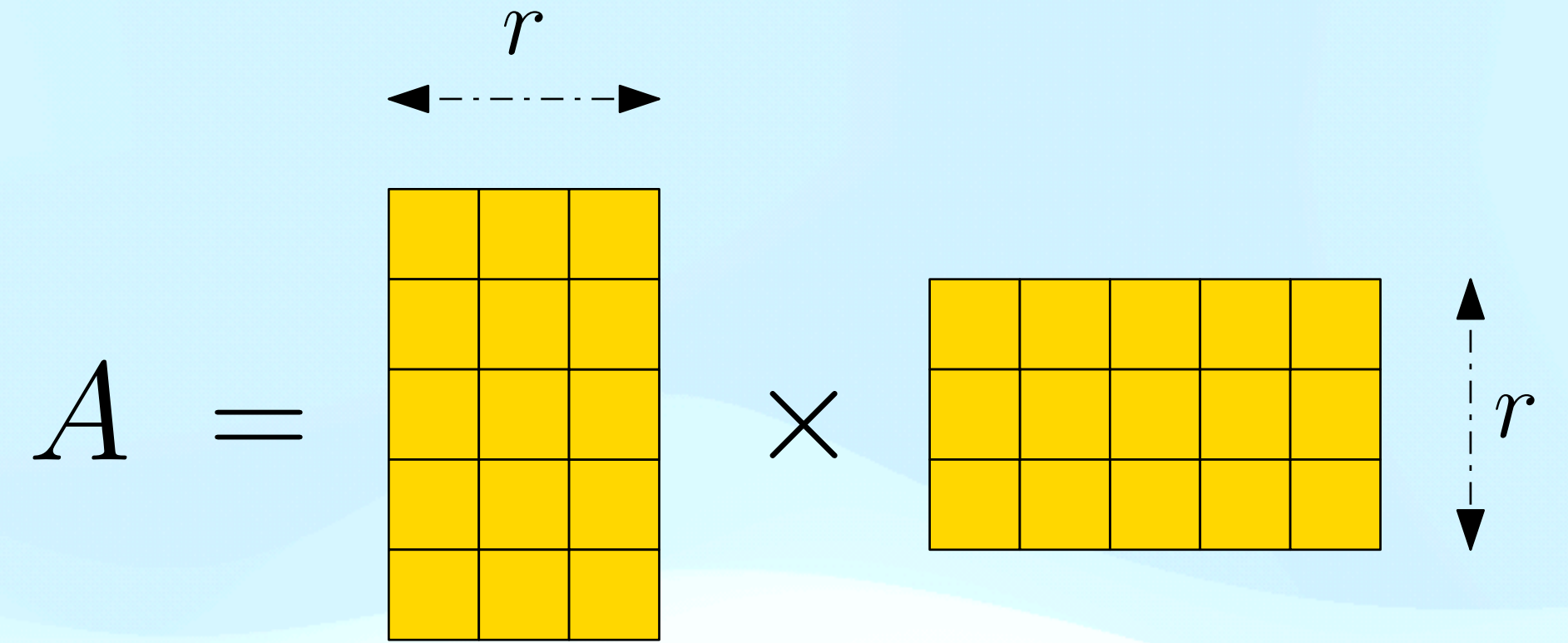
**SUPPORT CONSTRAINTS**



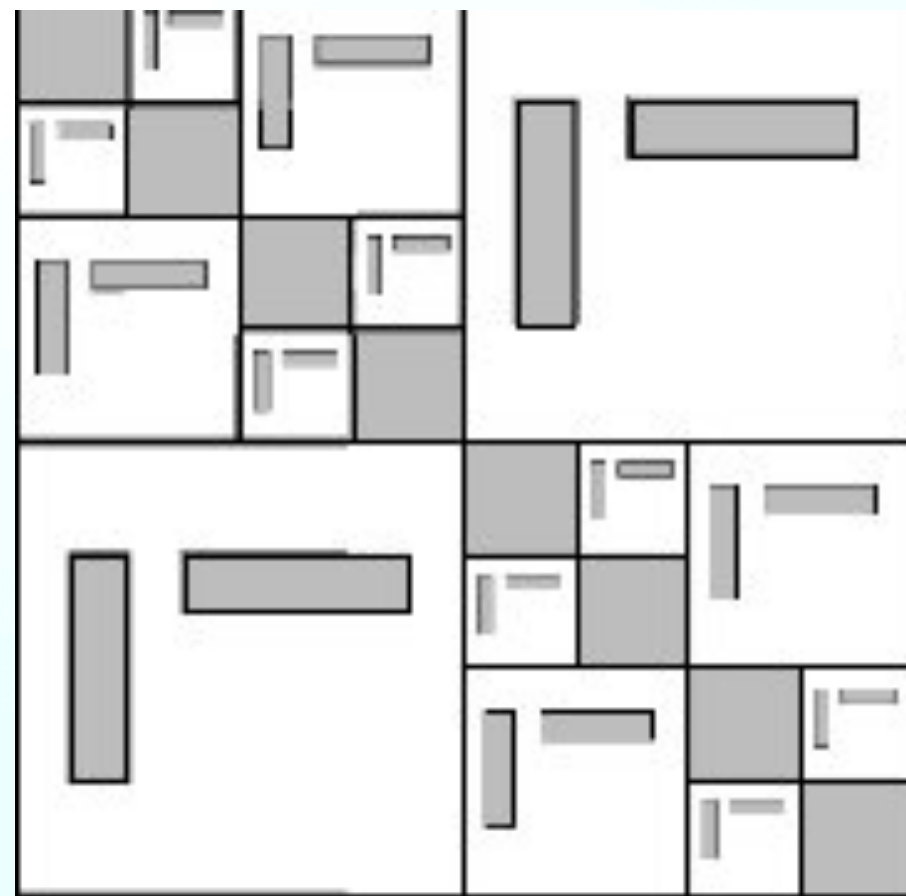
# Why Fixed Support Matrix Factorization?



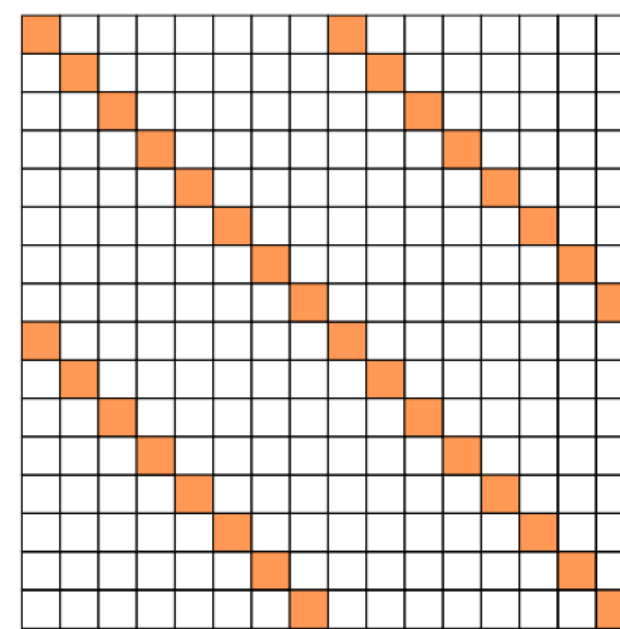
LU decomposition



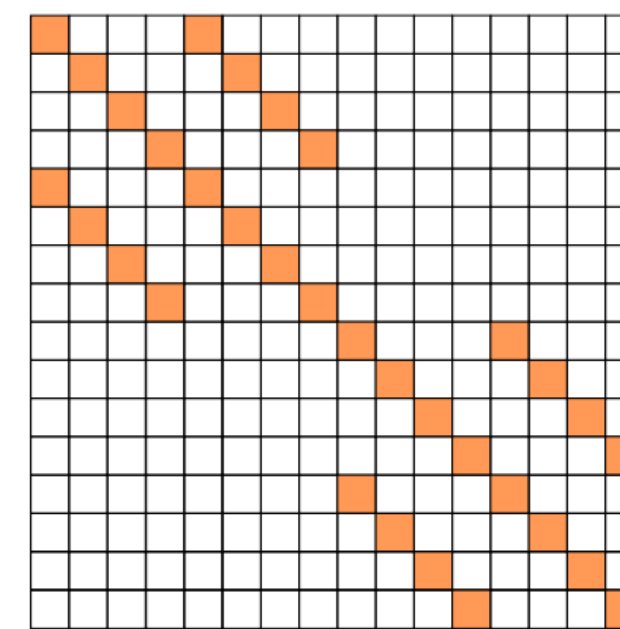
Low rank approximation



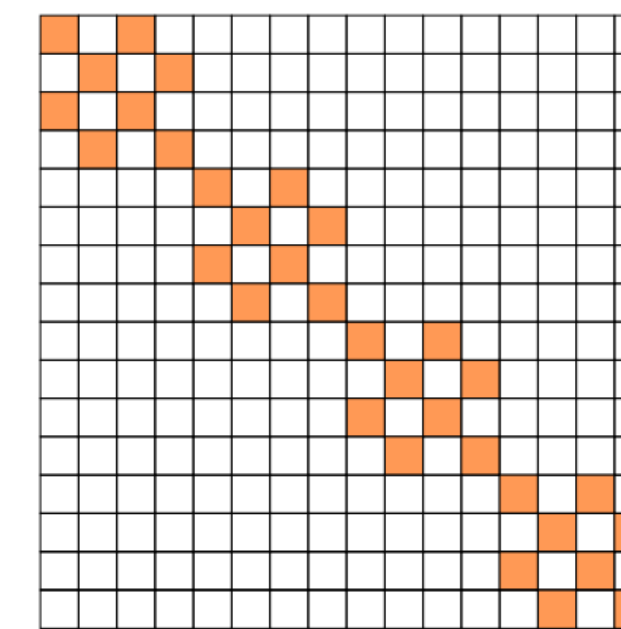
Hierarchical matrix



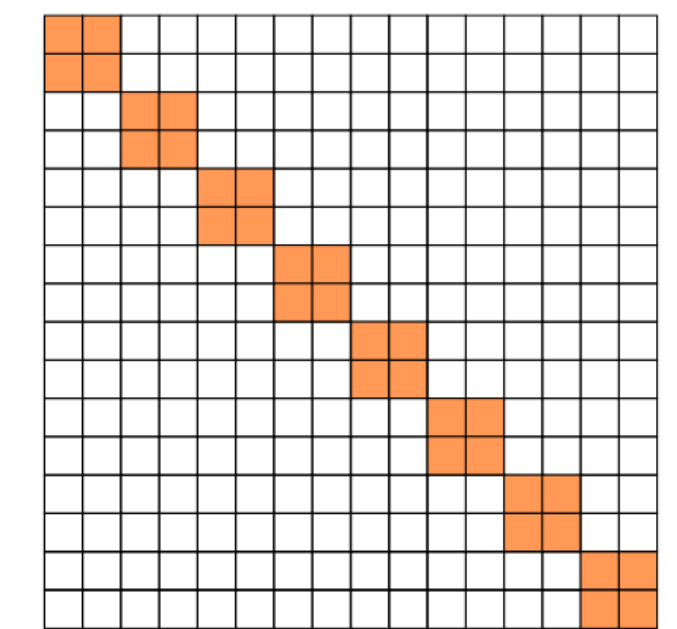
(a)  $S_{bf}^{(4)}$



(b)  $S_{bf}^{(3)}$



(c)  $S_{bf}^{(2)}$



(d)  $S_{bf}^{(1)}$

Butterfly matrix/factorization

# Known results on (FSMF)

- For arbitrary  $(I, J)$ , (FSMF) is *NP-hard* to solve.

NP-hardness

- There are instances  $(A, I, J)$  where (FSMF) has no optimal solution.

Ill-posedness

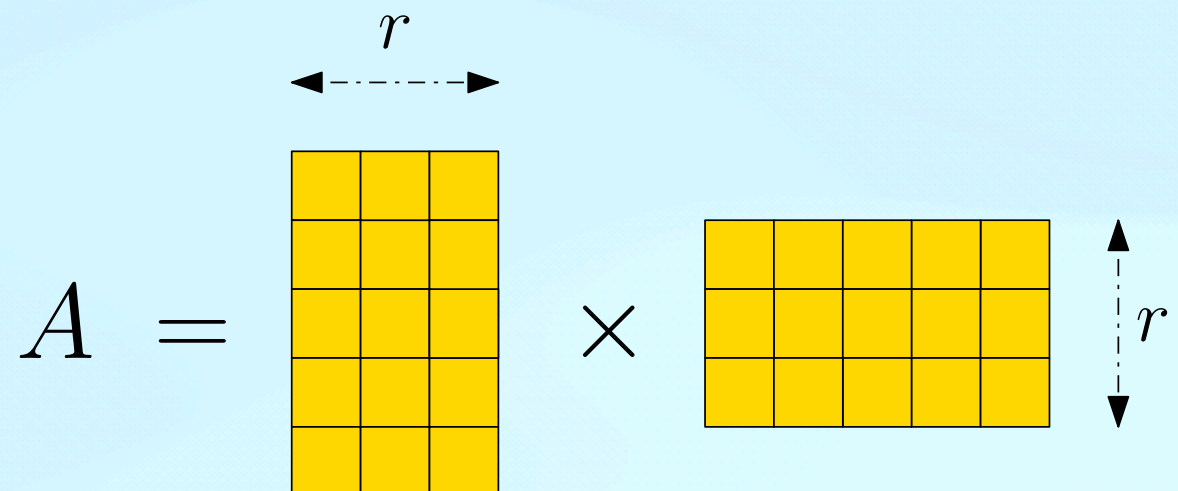
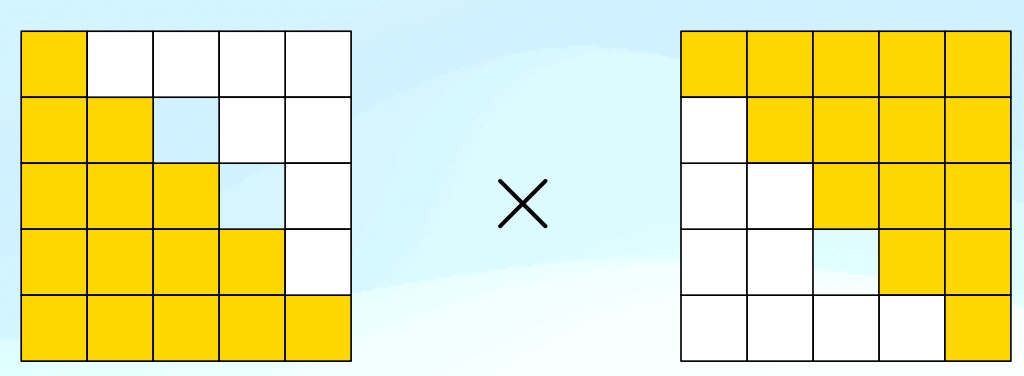
- For certain structured  $(I, J)$ , (FSMF) has a polynomial algorithm.

Tractability

- With the same family of structured  $(I, J)$ , loss function of (FSMF) has no local minima.

Benign landscape

# Existence of optimal solutions of FSMF

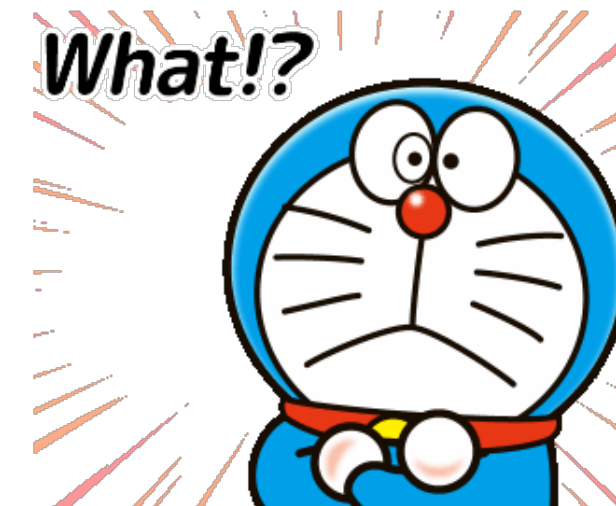
Low rank matrix approximation	LU decomposition
 $A = \begin{matrix} \xrightarrow{r} \\ \begin{matrix} \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \end{matrix} \\ \times \\ \begin{matrix} \begin{matrix} \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \end{matrix} \\ \uparrow r \end{matrix}$	 $A = \begin{matrix} \begin{matrix} \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \end{matrix} \\ \times \\ \begin{matrix} \begin{matrix} \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \\ \square & \square & \square & \square & \square \end{matrix} \end{matrix}$
<ul style="list-style-type: none"> <li>• Approximate a matrix <math>A</math> by a rank <math>r</math> matrix.</li> <li>• Optimal solutions are given by computing the truncated Singular Value Decomposition for <i>any</i> matrix <math>A</math>.</li> </ul>	<ul style="list-style-type: none"> <li>• <math>A = \begin{pmatrix} 0 &amp; 1 \\ 1 &amp; 0 \end{pmatrix}, I = \begin{pmatrix} 1 &amp; 0 \\ 1 &amp; 1 \end{pmatrix}, J = \begin{pmatrix} 1 &amp; 1 \\ 0 &amp; 1 \end{pmatrix}</math></li> <li>• Infimum is zero.</li> <li>• <math>A</math> cannot be factorised into lower and upper-triangular matrices.</li> </ul>

Huh...  
That's pretty good.

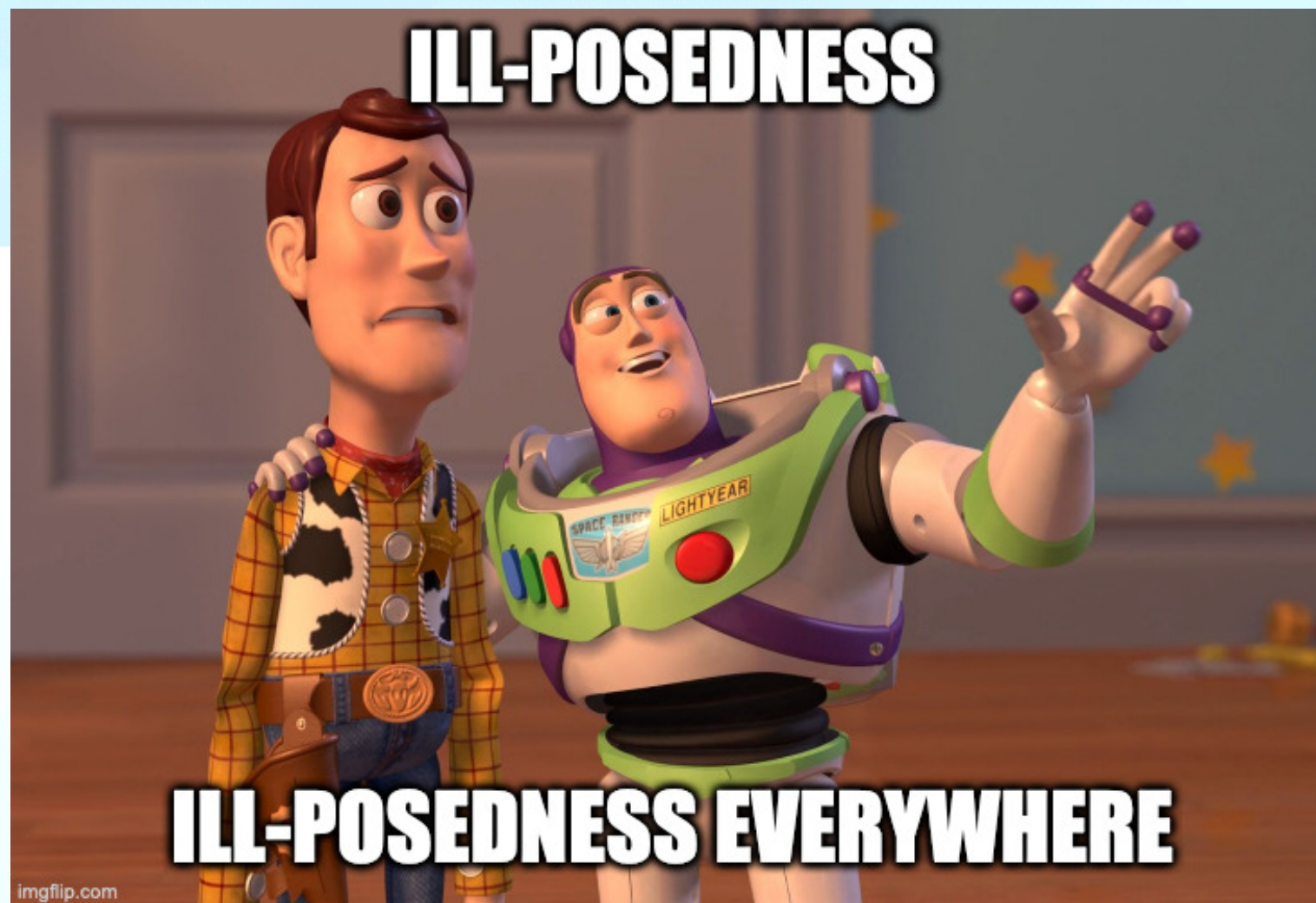


WELL-POSED

ILL-POSED



# Similar phenomenon

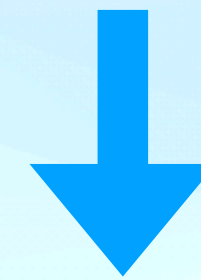


Tensor decomposition (order at least three)	<b>TENSOR RANK AND THE ILL-POSEDNESS OF THE BEST LOW-RANK APPROXIMATION PROBLEM</b> VIN DE SILVA* AND LEK-HENG LIM†
Matrix Completion	Low-Rank Matrix Approximation with Weights or Missing Data is NP-hard Nicolas Gillis <sup>1</sup> and François Glineur <sup>1</sup>
Robust Principle Component Analysis	Matrix rigidity and the ill-posedness of Robust PCA and matrix completion* Jared Tanner <sup>†‡</sup> Andrew Thompson <sup>§</sup> Simon Vary <sup>†</sup>
(Classical) Neural Network Training	<b>Best <math>k</math>-Layer Neural Network Approximations</b> Lek-Heng Lim <sup>1</sup> · Mateusz Michałek <sup>2,3</sup> · Yang Qi <sup>4</sup>

# Existence of optimal solutions of FSMF (cont)



Given support constraints  $(I, J)$ , is there a matrix  $A$  that makes (FSMF) have no optimal solution?



Given support constraints  $(I, J)$ , is there a data set  $\mathcal{D}$  that makes the training sparse ReLU NNs have no optimal solutions?

$$\min_{W^{(j)}, b^{(j)}}$$

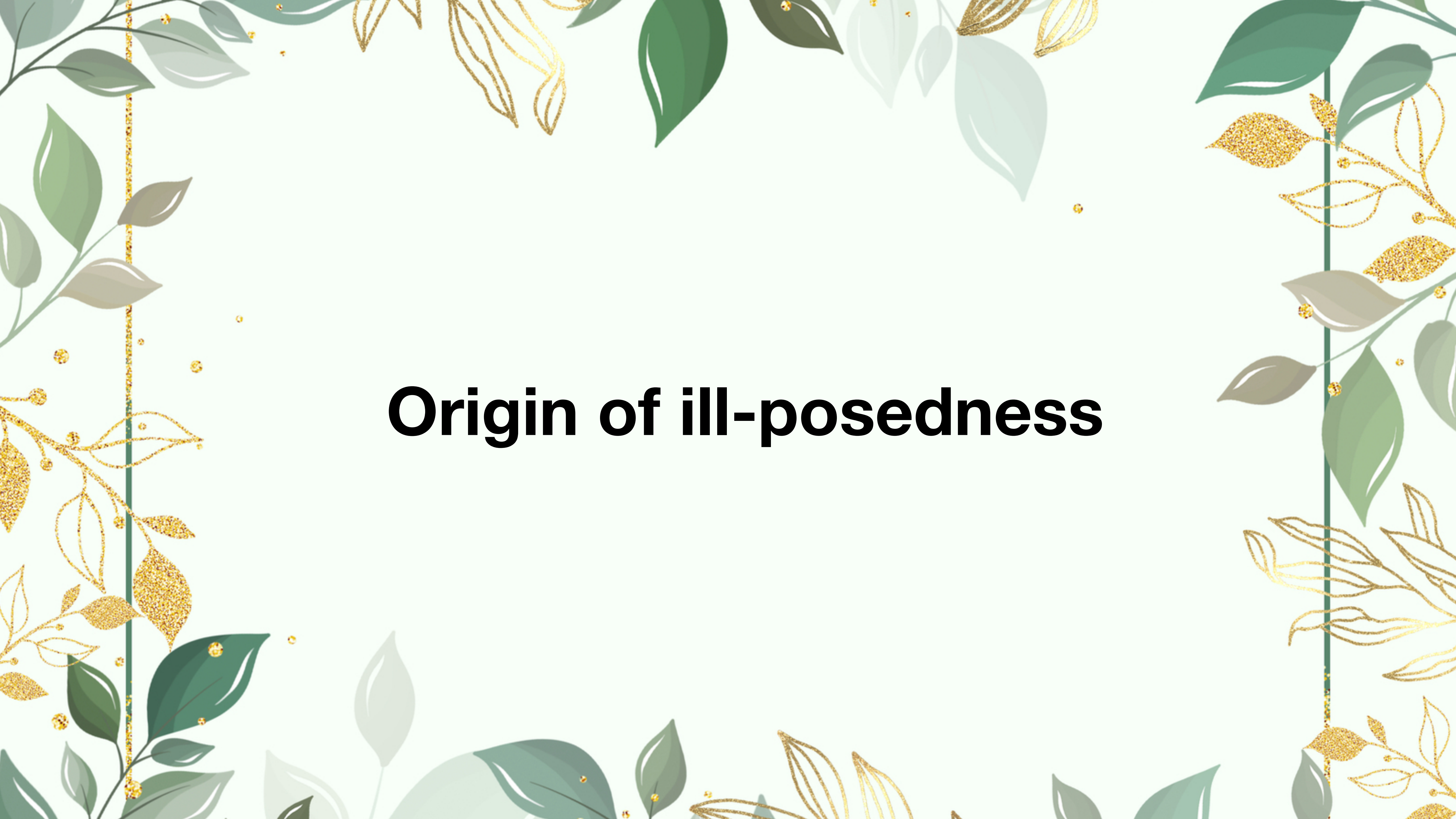
$$\|Y - W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

subject to:

$$W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$

$\mathcal{E}_j$ : set of matrices whose **support** are *fixed*.

Similar assumption to (FSMF)

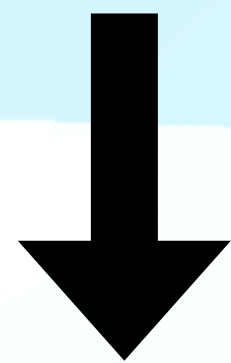
The background features a light green and white color palette. It is decorated with various green leaves of different shapes and sizes, some with gold glitter outlines or accents. The leaves are scattered across the page, with some appearing as solid green shapes and others as gold glitter outlines. The overall aesthetic is clean, modern, and nature-inspired.

# Origin of ill-posedness

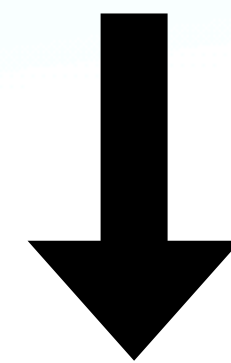
# Reformulation of (FSMF)

ORIGINAL  
FORMULATION

$$\min_{X,Y} \|A - XY^T\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$



Change of variables



NEW  
FORMULATION

$$\min_{B \in \mathcal{E}_{I,J}} \|A - B\|_F^2 \text{ where } \mathcal{E}_{I,J} := \{XY^T \mid \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J\}$$

**PROJECTION  $A$  ONTO THE SET  $\mathcal{E}_{I,J}$**

# Equivalence: closedness - well-posedness

A NECESSARY AND SUFFICIENT CONDITION

## THEOREM

$(I, J)$  is well-posed if and only if  $\mathcal{E}_{I,J}$  is a closed set in the usual topology of  $\mathbb{R}^{m \times n}$

## REMINDER:

**A set  $X$  is closed if the limit of any convergent sequence of elements of  $X$  is an element of  $X$ .**



# Equivalence: closedness - well-posedness

## PROOF

$\Rightarrow$  If  $(I, J)$  is well-posed:

By contradiction, assume that  $\mathcal{E}_{I,J}$  is not closed.

By definition, there exists  $A \notin \mathcal{E}_{I,J}$  such that there is a sequence  $\{B_n\}_{n \in \mathbb{N}}, B_n \in \mathcal{E}_{I,J}$  s.t.:

$$\lim_{n \rightarrow \infty} B_n = A.$$

Consider the (FSMF) with  $(A, I, J)$ :

- The infimum is zero (take the sequence  $\{B_n\}_{n \in \mathbb{N}}$ )
- The infimum is not attained ( $A \notin \mathcal{E}_{I,J}$ )

# Equivalence: closedness - well-posedness

## PROOF (CONT)

⇒ If  $\mathcal{E}_{I,J}$  is closed:

⇒ Since  $0 \in \mathcal{E}_{I,J}$  is closed, for *any* instance of (FSMF) with  $(A, I, J)$ , the infimum is at most  $C = \|A\|_F^2$ .

$$\min_B \|A - B\|_F^2 \text{ where } B \in \mathcal{E}_{I,J} \cap \mathbf{B}(A, \|A\|_F)$$

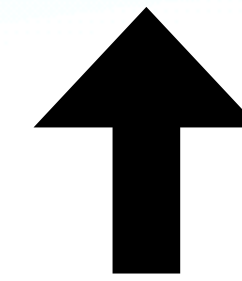
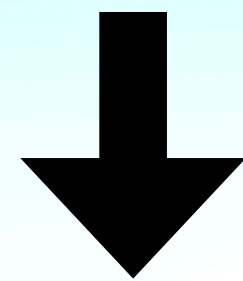
Ball centered at  $A$   
and radius  $\|A\|_F$

Important trick:  $\mathcal{E}_{I,J} \cap \mathbf{B}(A, \|A\|_F)$  is compact (bounded and closed).

$\|A - \cdot\|_F^2$  is a continuous function.

# Conclusion

Given a support constraint  $(I, J)$ , decide whether  $(I, J)$  is **well-posed**.



Given a support constraint  $(I, J)$ , decide whether  $\mathcal{E}_{I,J}$  is **closed**.



**An algorithm to decide the  
closedness of  $\mathcal{E}_{I,J}$**

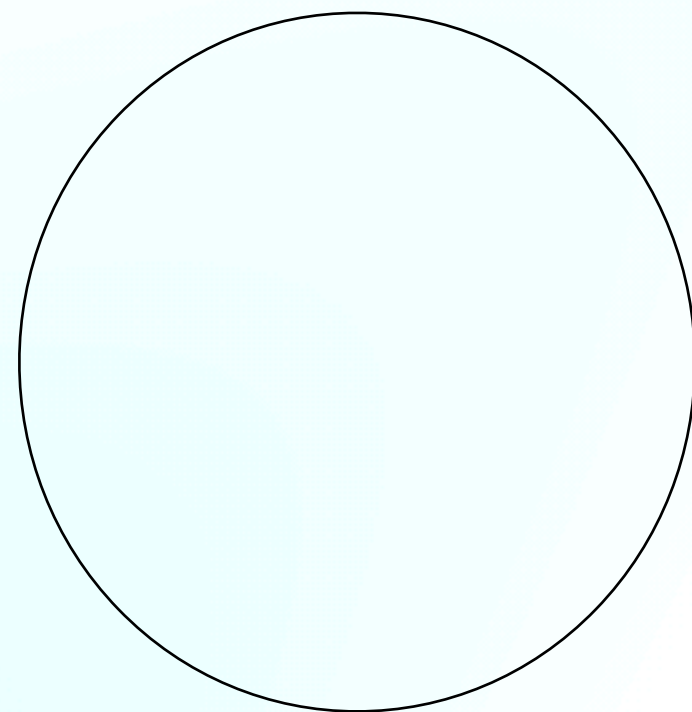
# Real algebraic geometry and its algorithm

## SEMI-ALGEBRAIC SET

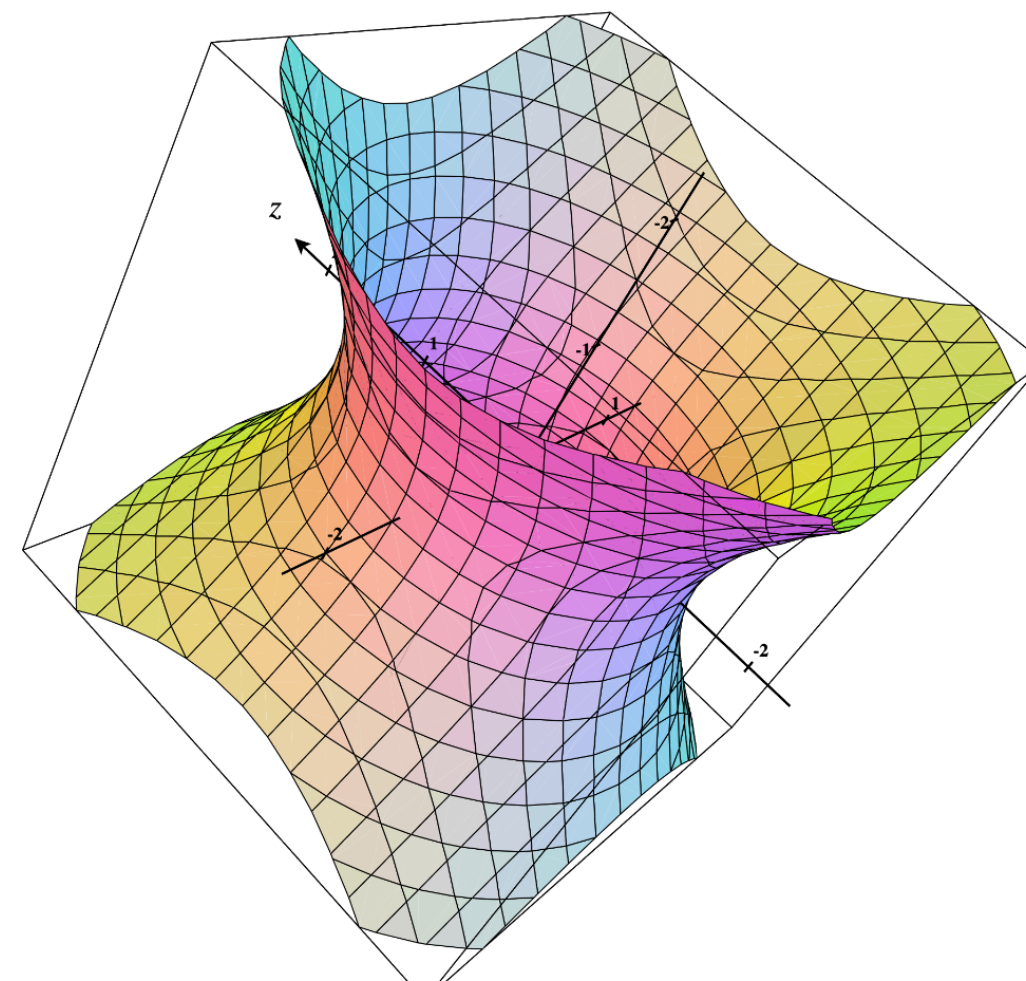
$$\bigcup_{i \in \mathcal{I}} \{x \in \mathbb{R}^n \mid P_i(x) = 0 \wedge \bigwedge_{j=1}^{\ell} Q_{i,j}(x) > 0\}, \mathcal{I} \text{ is finite}$$

where  $P_i, Q_{i,j}$  are polynomials

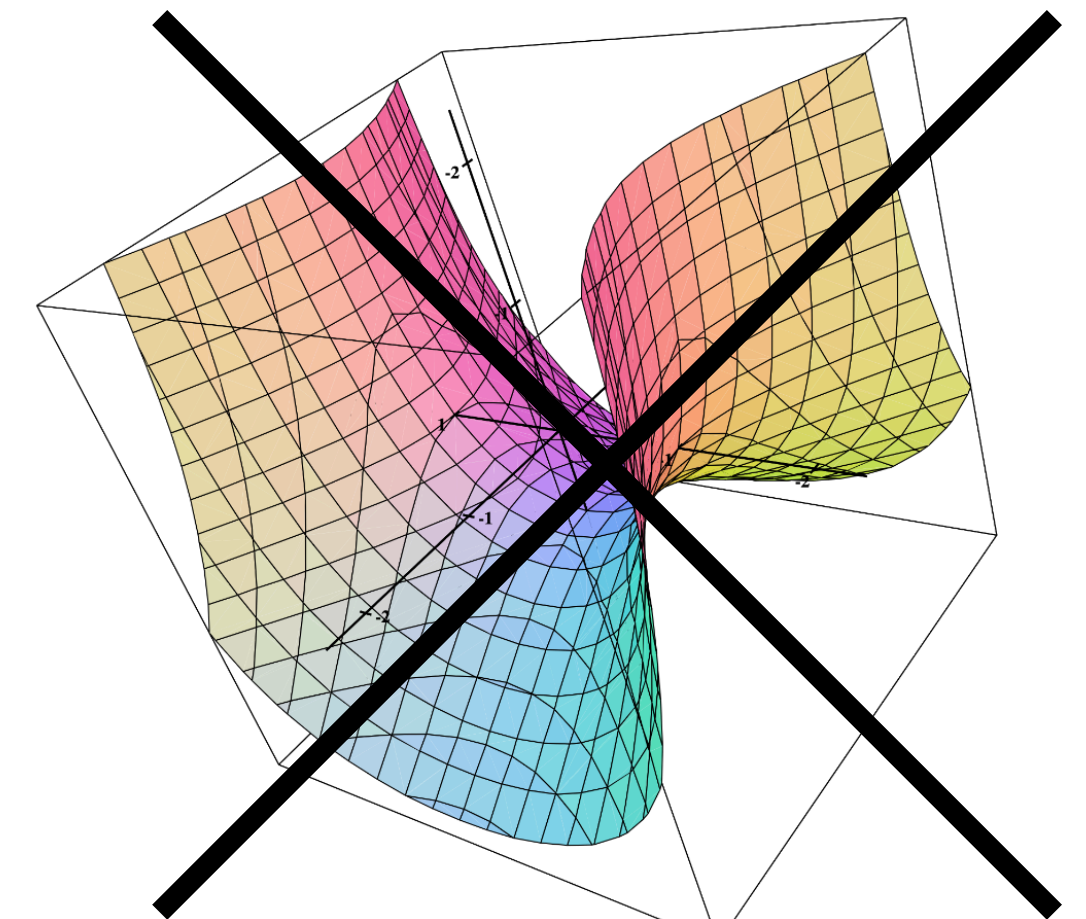
### EXAMPLE:



$$\{(x, y) \mid x^2 + y^2 = 1\}$$



$$\{(x, y, z) \mid x^2 - y^2 + z^2 = 2\}$$



$$\{(x, y, z) \mid x^2 - y^2 + e^z = 2\}$$

# $\mathcal{E}_{I,J}$ is a semi-algebraic set

## THEOREM

For any  $(I, J)$ ,  $\mathcal{E}_{I,J}$  is a semi-algebraic set

**REMINDER:**  $\mathcal{E}_{I,J} := \{XY^T \mid \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J\}$



How to find the set of polynomials describing  $\mathcal{E}_{I,J}$ ?

## PROJECTION THEOREM

Let  $X$  be semi-algebraic,  $Y = \{y \mid \exists x, (x, y) \in X\}$  is also semi-algebraic

# $\mathcal{E}_{I,J}$ is a semi-algebraic set (cont)

## PROJECTION THEOREM

Let  $X$  be semi-algebraic,  $Y = \{y \mid \exists x, (x, y) \in X\}$  is also semi-algebraic.

## PROOF (THAT $\mathcal{E}_{I,J}$ IS SEMI-ALGEBRAIC):

Consider  $\mathcal{A} := \{(A, X, Y) \mid \|A - XY^\top\|_F^2 = 0 \wedge \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J\}$ .

Therefore,  $\mathcal{A}$  is semi-algebraic.

polynomial

$X_{i,j} = 0, \forall (i, j) \notin I$

$Y_{i,j} = 0, \forall (i, j) \notin J$

To conclude, projection of  $\mathcal{A}$  to the first term is  $\mathcal{E}_{I,J}$  (because  $\|A - XY^\top\|_F^2 = 0 \Rightarrow A = XY^\top$ )

→ Therefore, we can use tools from real algebraic geometry to decide the closedness of  $\mathcal{E}_{I,J}$

# Deciding the closedness of $\mathcal{E}_{I,J}$

$\mathcal{E}_{I,J}$  is a closed set if and only if  $\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$  is empty

**REMINDER:** Given a set  $\mathcal{A}$ ,  $\overline{\mathcal{A}}$  is the set of limits of sequence of  $\mathcal{A}$ .

$$\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J} =$$

$$\{A \mid \forall X, \forall Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^T\|^2 > 0\}$$

$$\mathcal{E}_{I,J}^C$$

$$\bigcap \{A \mid \forall \epsilon > 0, \exists X, \exists Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^T\|^2 < \epsilon\}$$

$$\overline{\mathcal{E}_{I,J}}$$

→ Using (generalised) projection theorem,  $\mathcal{E}_{I,J}^C$ ,  $\overline{\mathcal{E}_{I,J}}$ ,  $\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$  are semi-algebraic sets



# Deciding the closedness of $\mathcal{E}_{I,J}$

$$\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J} = \{A \mid \forall X, \forall Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^T\|^2 > 0\}$$

$$\bigcap \{A \mid \forall \epsilon > 0, \exists X, \exists Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^T\|^2 < \epsilon\}$$

- Using *quantifier elimination algorithm*, we can decide the emptiness of the semi-algebraic set  $\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$ . (S. Basu, R. Pollack, M-F Roy, *Algorithms in Real Algebraic Geometry*)

- The complexity of the algorithm is  $O\left(4^{C^k}\right)$ , where:

- $C$  is a universal constant.
- $k = mn + 2(|I_1| + |I_2|) + 1$

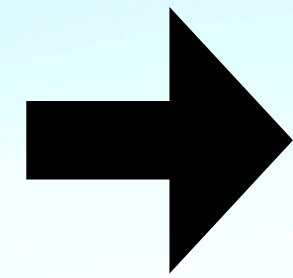


Size of the matrix product

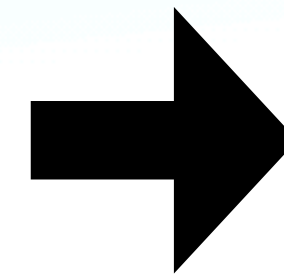
Size of the supports

# Recap of the algorithm

$(I, J)$  is  
well-posed?



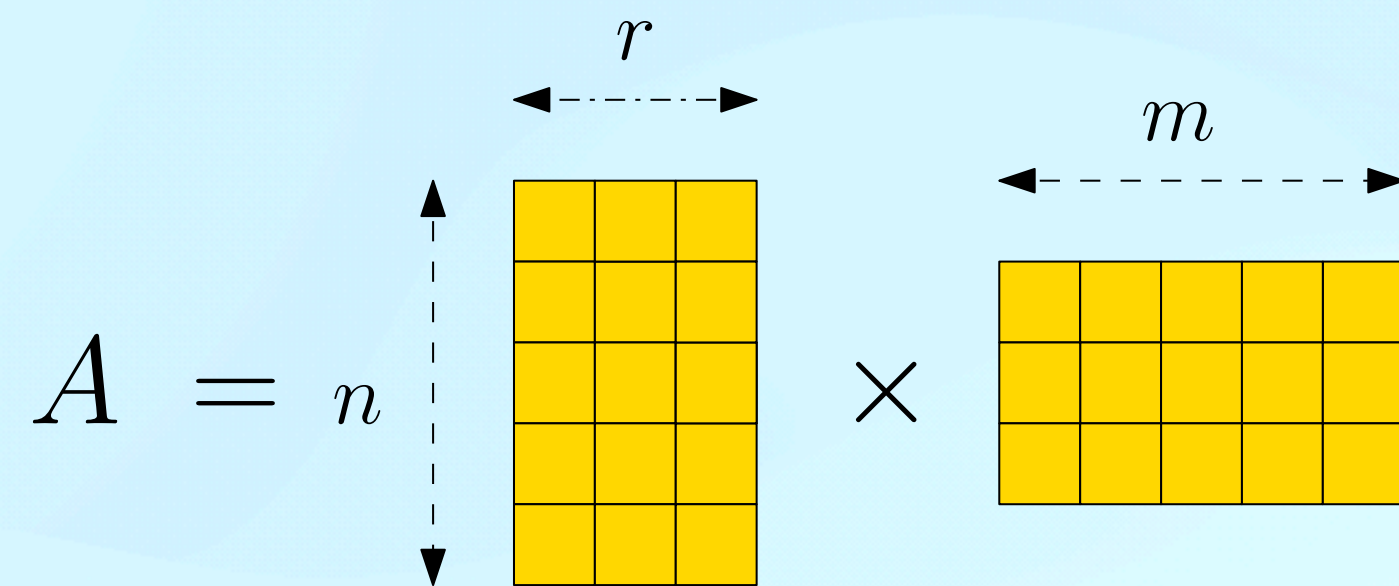
$\mathcal{E}_{I,J}$  is  
closed?



$\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$   
is empty?

# How does the algorithm work in practice?

## Low rank approximation



✓  $m = n = r = 2$

✗  $m = n = 3, r = 2$

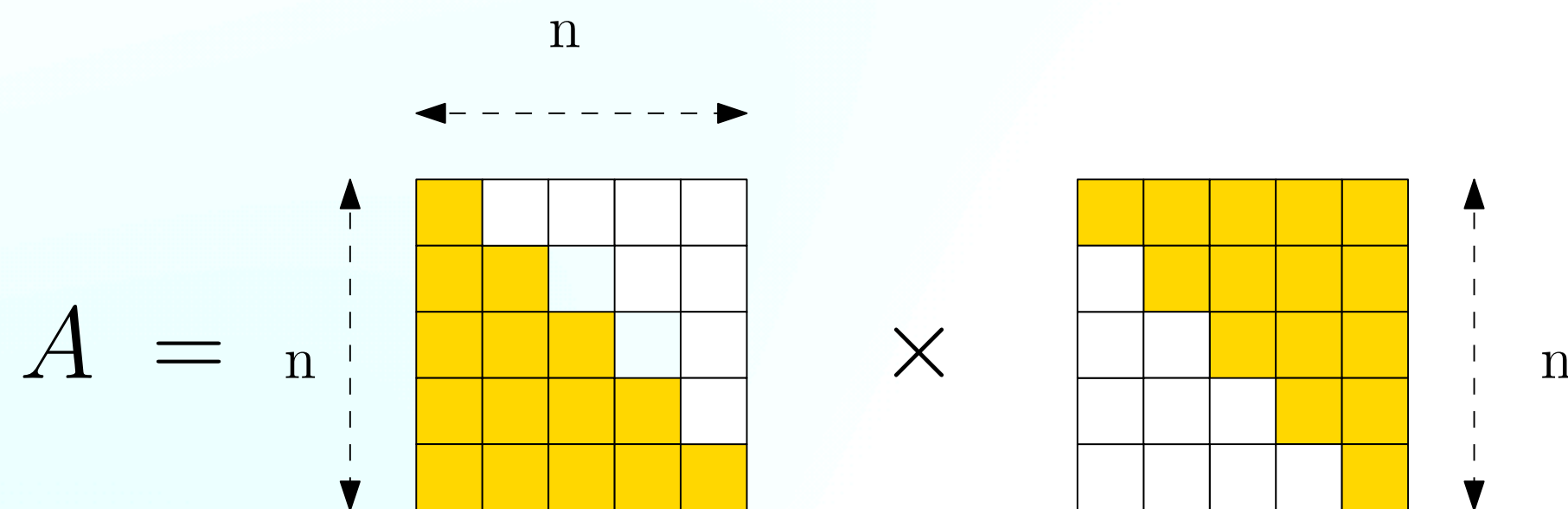
```

quantifiersElimination --zsh-- 80x24
[(base) tung@dhcp-67-169 quantifiersElimination % python fullsupport.py
Running time: 0.0036940574645996094
True
    
```

```

quantifiersElimination --zsh-- 80x24
[(base) tung@dhcp-67-169 quantifiersElimination % python fullsupport.py
^CRunning time: 2112.0239312648773
None
    
```

## LU decomposition



✓  $n = 2$

✗  $n = 3$

```

quantifiersElimination --zsh-- 80x24
[(base) tung@dhcp-67-169 quantifiersElimination % python LU2x2.py
Running time: 0.013816118240356445
False
    
```

```

quantifiersElimination --zsh-- 80x24
[(base) tung@dhcp-67-169 quantifiersElimination % python LU3x3.py
^CRunning time: 3202.279525756836
None
    
```

# Perspectives

- ✓ Given support constraint  $(I, J)$ , its well-posedness is ***decidable***.
- ✓ The algorithm generalises easily to multi-factors  $(L > 2)$ .

But,

- ✗ The complexity for the algorithm is doubly exponential.
- ✗ Using quantifier elimination algorithm (a general algorithm) does not provide any insight properties of  $\mathcal{E}_{I,J}$ .



# **Well-posedness of sparse ReLU neural networks**

# Fixed support sparse ReLU neural networks

Given data set  $\mathcal{D} := (X, Y)$ , solve:

GENERAL

$$\begin{aligned} \min_{W^{(j)}, b^{(j)}} \quad & \|Y - W^{(L)} \sigma(\dots \sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2 \\ \text{subject to:} \quad & W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\} \end{aligned}$$



FIXED SUPPORT

$$\begin{aligned} \min_{W^{(j)}, b^{(j)}} \quad & \|Y - W^{(L)} \sigma(\dots \sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2 \\ \text{subject to:} \quad & \text{supp}(W^{(j)}) \in I_j, \forall j \in \{1, \dots, L\} \end{aligned}$$

# DÉJÀ VU: closedness vs well-posedness



Given a support constraint  $(I_1, \dots, I_L)$ , is the training problem well-posed (i.e., for all data set  $\mathcal{D}$ , optimal solutions always exist)?

The support constraint  $(I_1, \dots, I_L)$  make training problem **well-posed** if and only if for all input sets  $X$ , the image  $W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}$  is **closed**.



# Sufficient condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with **output dimension** equal to **one**, any support constraint makes the training problem **well-posed**.

## COROLLARY

For **two-layer** neural networks ( $L = 2$ ) with **output dimension** equal to **one**, constraints  $\mathcal{E}_j := \{X \mid \|X\|_0 \leq k_j\}, j = 1, 2$  makes the training problem well-posed.



# Necessary condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with support constraint  $(I, J)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I,J}$ .

this is decidable



## THEOREM

For fixed support neural networks with support constraint  $(I_1, \dots, I_L)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I_1, \dots, I_L}$ .

# Necessary condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with support constraint  $(I, J)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I,J}$ .

The condition is just necessary because when there is **no constraint** on the support, the training problem is ill-posed for certain data set.

(L-H. Lim, M. Michalek, Y. Qi, *Constructive Approximation* 2019)

# Contribution and future works

## TAKE AWAY MESSAGE

- Ill-posedness of (FSMF) is decidable, not yet tractable.
- Link between sparse matrix factorization and sparse ReLU neural networks.

## POSSIBLE IMPROVEMENT?

- Better algorithms to decide the ill-posedness of (FSMF)
- When the problem is well-posed, is there polynomial algorithm for (FSMF)
- A full characterization of ill-posedness of sparse ReLU neural networks

<https://arxiv.org/abs/2306.02666>

**THANK YOU**